

Functional Correlation Clustering with Applications in Cancer Genomics

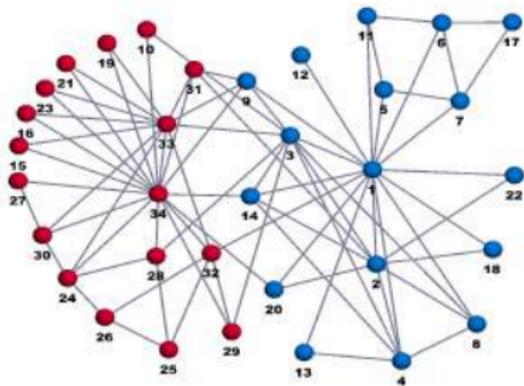
Presenter: Gregory J. Puleo

Joint work with A. Emad, J. Hou, J. Ma and O. Milenkovic

Coordinated Science Laboratory
University of Illinois at Urbana-Champaign

2015 MBMC Workshop
University of Southern California
December 4, 2015

Community Detection and Recovery



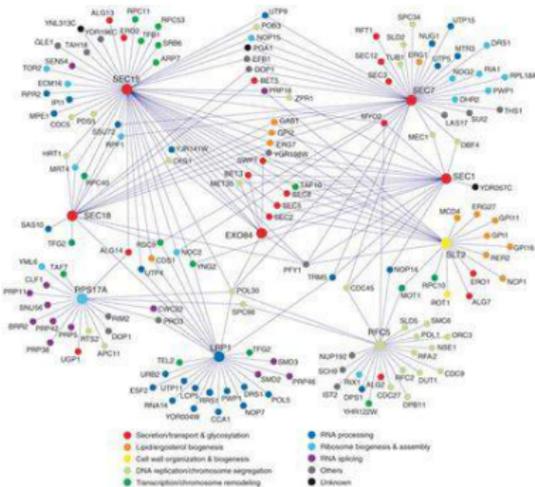
- **Social networks:** given pairwise connections (friendships) between individuals, identify “communities” using **edge density** information. (Undirected graphs)

Zachary's karate club graph
(Zachary 1977)

Image source:

ifisc.uib-csic.es/jramasco/ComplexNets

Community Detection and Recovery

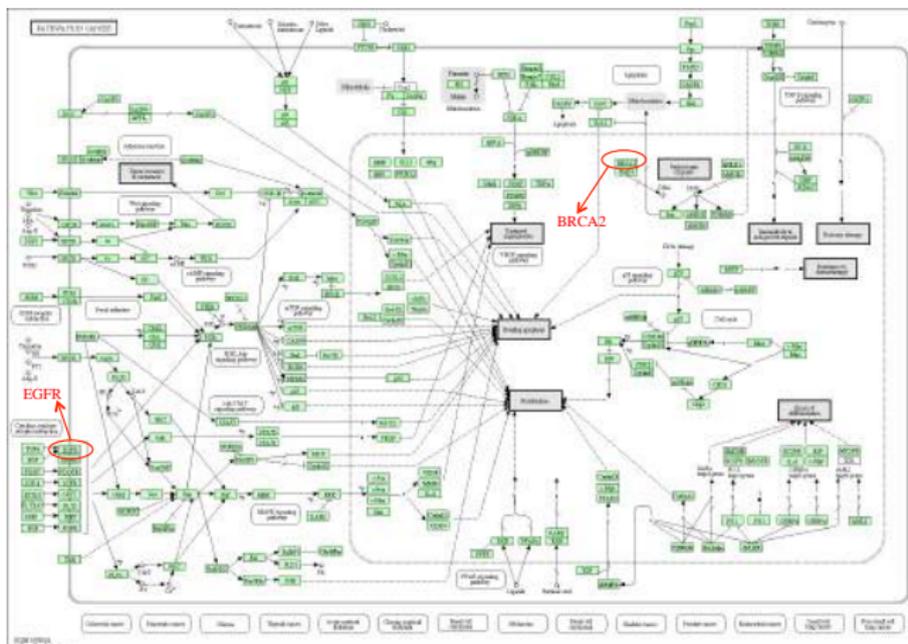


Gene regulatory networks
(Davierwala et al. 2005)

- **Social networks:** given pairwise connections (friendships) between individuals, identify “communities” using **edge density** information. (Undirected graphs)
- **Gene networks:** given activating and suppressing interactions between genes, identify **dense gene pathways**. (Directed graphs)

Motivating Problem: Cancer Driver “Modules”

Significant recent interest in “cancer driver mutation” analysis. Driver mutations responsible for tumorigenesis, unlike neutral passenger mutations.

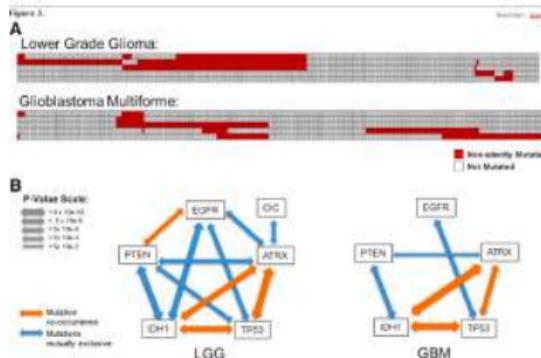


Motivating Problem: Cancer Driver “Modules”

- Significant recent interest in “cancer driver mutation” analysis. Driver mutations responsible for tumorigenesis, unlike neutral passenger mutations. Drivers obey:

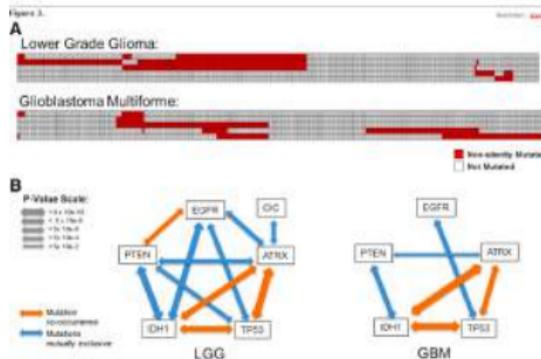
Motivating Problem: Cancer Driver “Modules”

- Significant recent interest in “cancer driver mutation” analysis. Driver mutations responsible for tumorigenesis, unlike neutral passenger mutations. Drivers obey:
- **Mutual exclusivity principle:** at most one mutation per pathway.



Motivating Problem: Cancer Driver “Modules”

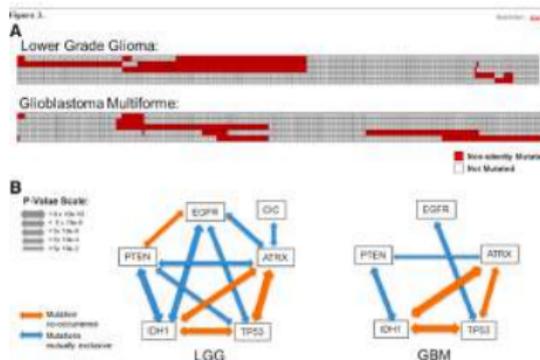
- Significant recent interest in “cancer driver mutation” analysis. Driver mutations responsible for tumorigenesis, unlike neutral passenger mutations. Drivers obey:
- **Mutual exclusivity principle:** at most one mutation per pathway.



- **Pathway coverage property:** Important pathways mutated in majority of patients.

Motivating Problem: Cancer Driver “Modules”

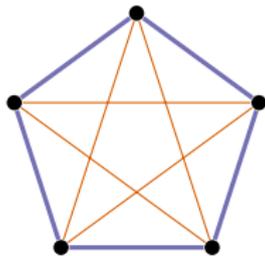
- Significant recent interest in “cancer driver mutation” analysis. Driver mutations responsible for tumorigenesis, unlike neutral passenger mutations. Drivers obey:
- **Mutual exclusivity principle:** at most one mutation per pathway.



- **Pathway coverage property:** Important pathways mutated in majority of patients.
- **Pathway constraints:** Number of driver pathways unknown, sizes “mostly” limited to 6-15 genes.

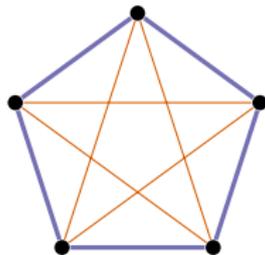
Functional Community Detection: Correlation Clustering

- Correlation clustering (clustering with qualitative information) was introduced by Bansal, Blum, and Chawla (FOCS '02).



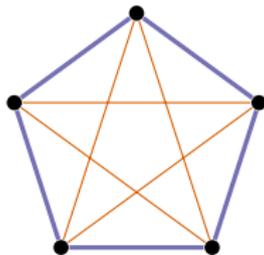
Functional Community Detection: Correlation Clustering

- Correlation clustering (**clustering with qualitative information**) was introduced by Bansal, Blum, and Chawla (FOCS '02).
- Basic formulation: one is given n objects and, for some pairs of objects, a judgment whether they are **similar** or **dissimilar**. Similarity may be assessed based on given data.



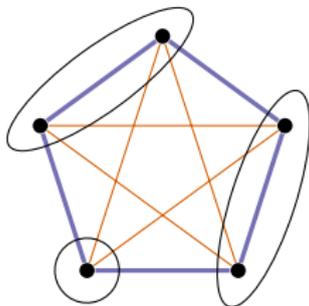
Functional Community Detection: Correlation Clustering

- Correlation clustering (**clustering with qualitative information**) was introduced by Bansal, Blum, and Chawla (FOCS '02).
- Basic formulation: one is given n objects and, for some pairs of objects, a judgment whether they are **similar** or **dissimilar**. Similarity may be assessed based on given data.
- Represent constraints via graph G with edges labeled $+$ or $-$.



Functional Community Detection: Correlation Clustering

- Correlation clustering (**clustering with qualitative information**) was introduced by Bansal, Blum, and Chawla (FOCS '02).
- Basic formulation: one is given n objects and, for some pairs of objects, a judgment whether they are **similar** or **dissimilar**. Similarity may be assessed based on given data.
- Represent constraints via graph G with edges labeled $+$ or $-$.
- **Goal:** Partition vertices into **clusters** by minimizing total number of $+$ edges between clusters and the number of $-$ edges within clusters.



Correlation Clustering: Basics

- Correlation Clustering does not require advance knowledge of number of clusters, and is a form of “agnostic learning.”

Correlation Clustering: Basics

- Correlation Clustering does not require advance knowledge of number of clusters, and is a form of “agnostic learning.”
- Related to cluster editing, graph partitioning, sparsest cut, balanced edge partitioning, rank aggregation...

Correlation Clustering: Basics

- Correlation Clustering does not require advance knowledge of number of clusters, and is a form of “agnostic learning.”
- Related to cluster editing, graph partitioning, sparsest cut, balanced edge partitioning, rank aggregation...
- Finding best clustering is NP-Hard (Bansal–Blum–Chawla), so we seek approximation algorithms.

Correlation Clustering: Basics

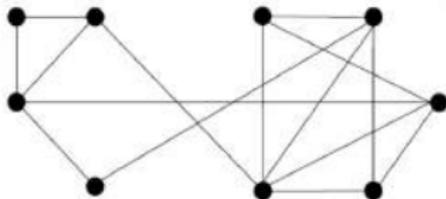
- Correlation Clustering does not require advance knowledge of number of clusters, and is a form of “agnostic learning.”
- Related to cluster editing, graph partitioning, sparsest cut, balanced edge partitioning, rank aggregation...
- Finding best clustering is NP-Hard (Bansal–Blum–Chawla), so we seek approximation algorithms.
- If underlying graph can have missing edges, probably no constant-factor approximation algorithm is possible. Thus, we assume the underlying graph is complete.

Correlation Clustering: Basics

- Correlation Clustering does not require advance knowledge of number of clusters, and is a form of “agnostic learning.”
- Related to cluster editing, graph partitioning, sparsest cut, balanced edge partitioning, rank aggregation...
- Finding best clustering is NP-Hard (Bansal–Blum–Chawla), so we seek approximation algorithms.
- If underlying graph can have missing edges, probably no constant-factor approximation algorithm is possible. Thus, we assume the underlying graph is complete.
- We discuss two algorithms: Ailon–Charikar–Newman (2008) and Charikar–Guruswami–Wirth (2005).

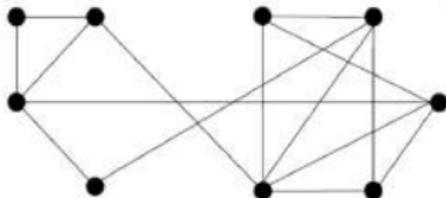
Algorithms: ACN Pivoting

- Start with complete graph with negative edges removed:

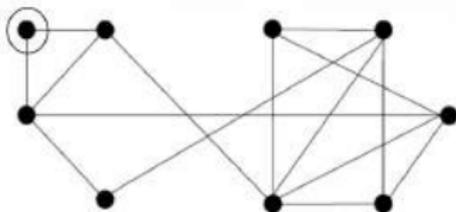


Algorithms: ACN Pivoting

- Start with complete graph with negative edges removed:

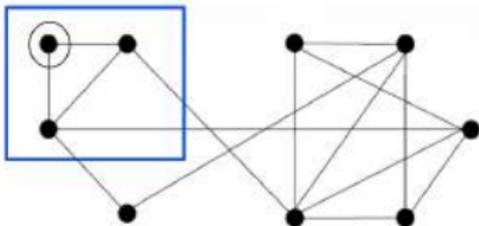


- Choose vertex uniformly at random:



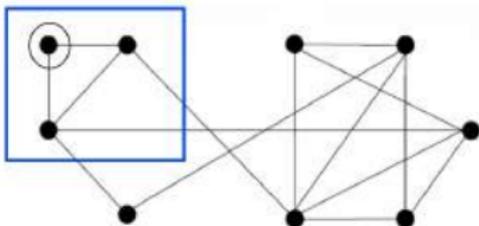
Algorithms: ACN Pivoting

- Form cluster from its neighborhood:

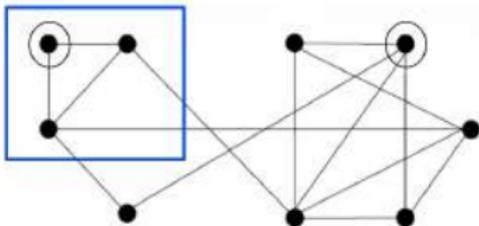


Algorithms: ACN Pivoting

- Form cluster from its neighborhood:

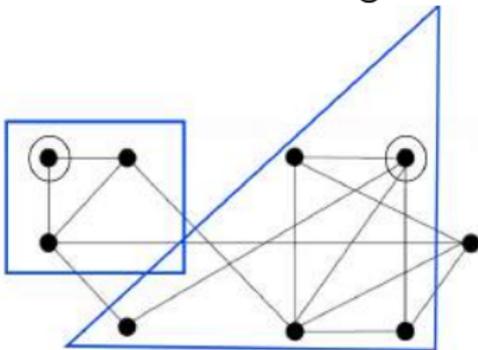


- Choose another vertex **uniformly at random**:



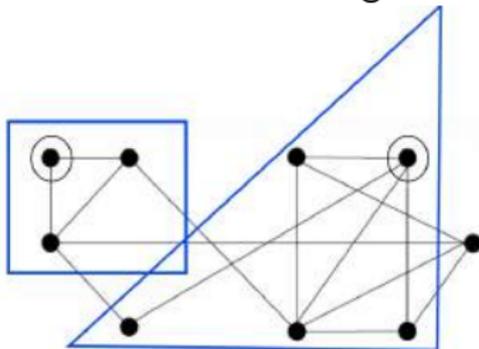
Algorithms: ACN Pivoting

- Form cluster from its neighborhood:



Algorithms: ACN Pivoting

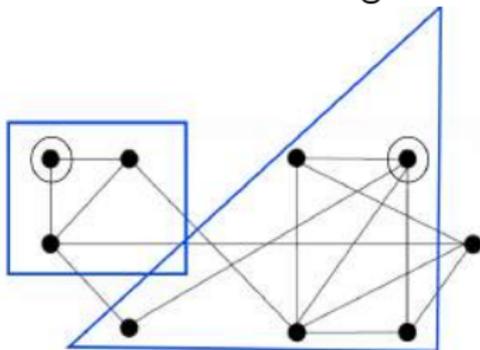
- Form cluster from its neighborhood:



- Continue.

Algorithms: ACN Pivoting

- Form cluster from its neighborhood:



- Continue.
- This yields a 3-approximation algorithm; can improve to 2.5 by solving an LP first.

Algorithms: CGW, Step 1 – LP Relaxation

Interpret $x_{uv} = 1$ as saying “ u and v are in different clusters”,
interpret $x_{uv} = 0$ as saying “ u and v are in the same cluster”.

Solve LP relaxation of integer formulation of correlation clustering:

$$\begin{aligned} & \underset{0 \leq x_e \leq 1}{\text{minimize}} && \sum_{e \in E^+(G)} x_e + \sum_{e \in E^-(G)} (1 - x_e) \\ & \text{subject to} && x_{uv} \leq x_{uz} + x_{zv} \quad (\forall \text{ distinct } u, v, z \in V(G)) \end{aligned}$$

Cost of optimal LP solution \leq cost of optimal clustering.

Algorithms: CGW, Step 2 – Rounding Up

Round up LP solution x to obtain clustering (region growing):

Let $S = V(G)$.

while $S \neq \emptyset$ **do**

Let the “pivot vertex” u be an arbitrary element of S .

Let $T = \{w \in S - \{u\} : x_{uw} \leq 1/2\}$.

if $\sum_{w \in T} x_{uw} \geq |T|/4$ **then**

Output the singleton cluster $\{u\}$.

Let $S = S - \{u\}$.

else

Output the cluster $\{u\} \cup T$.

Let $S = S - (\{u\} \cup T)$.

end if

end while

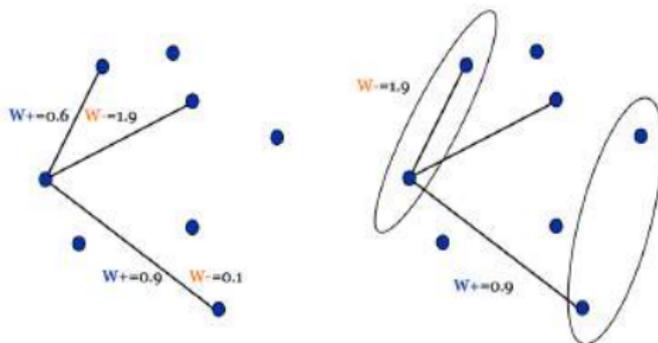
Cost of resulting clustering is ≤ 4 times cost of optimal clustering.

Extensions of the Basic Model: Edge Weights

- Ailon–Charikar–Newman also introduced *weighted* formulation: instead of $+/-$ labels, each edge e has weights $w_e^+, w_e^- \geq 0$.

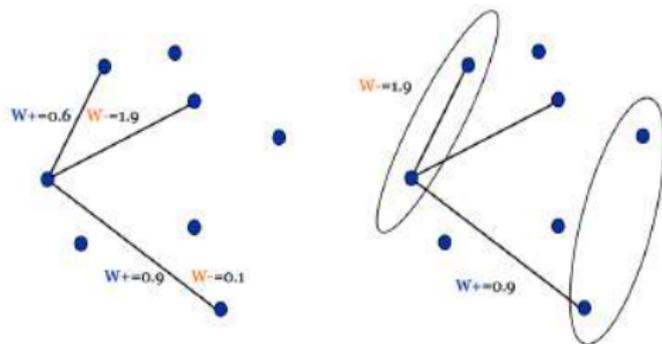
Extensions of the Basic Model: Edge Weights

- Ailon–Charikar–Newman also introduced *weighted* formulation: instead of $+/-$ labels, each edge e has weights $w_e^+, w_e^- \geq 0$.
- Edge e costs w_e^+ when placed between clusters and costs w_e^- when placed within a cluster.



Extensions of the Basic Model: Edge Weights

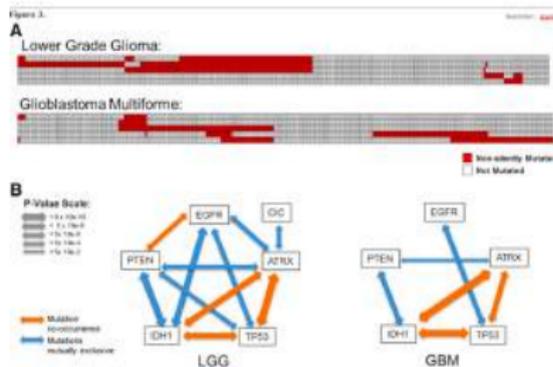
- Ailon–Charikar–Newman also introduced *weighted* formulation: instead of $+/-$ labels, each edge e has weights $w_e^+, w_e^- \geq 0$.
- Edge e costs w_e^+ when placed between clusters and costs w_e^- when placed within a cluster.



- **Known:** if all $w_e^+ + w_e^- = 1$ (“probability constraints”), there is a randomized expected 2.5-approximation algorithm (Ailon-Charikar-Newman).

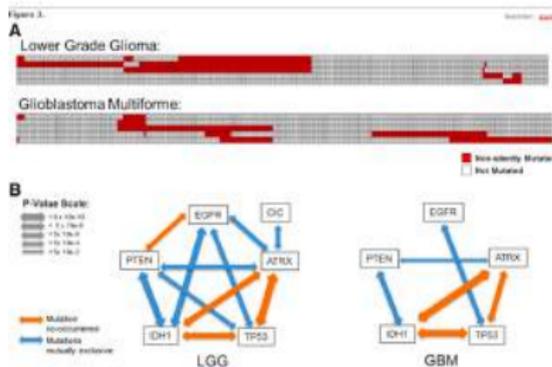
Recall Motivating Problem: Cancer Driver Modules

- **Mutual exclusivity principle:** at most one mutation per pathway.



Recall Motivating Problem: Cancer Driver Modules

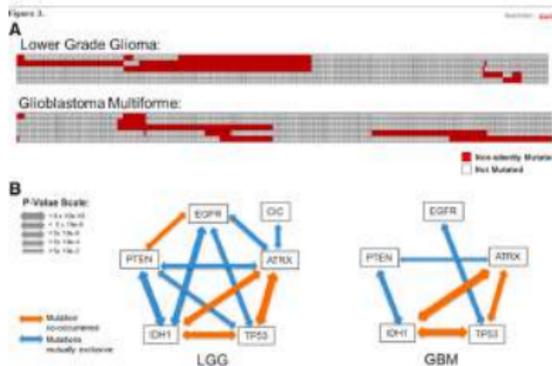
- **Mutual exclusivity principle:** at most one mutation per pathway.



- **Pathway coverage property:** Important pathways mutated in majority of patients.

Recall Motivating Problem: Cancer Driver Modules

- **Mutual exclusivity principle:** at most one mutation per pathway.



- **Pathway coverage property:** Important pathways mutated in majority of patients.
- **Pathways constraints:** Number unknown, sizes “mostly” limited to 6-15 genes.

Extensions: Size Constraints and New Weights

- Need to cover larger set of allowed weights and discourage “large” clusters in solution. In latter case, introduce a **size bound parameter** K , and give each vertex v a parameter $\mu_v \geq 0$.

Extensions: Size Constraints and New Weights

- Need to cover larger set of allowed weights and discourage “large” clusters in solution. In latter case, introduce a **size bound parameter** K , and give each vertex v a parameter $\mu_v \geq 0$.
- If v is in a cluster of size $K + 1 + y_v$, where $y_v \geq 0$, then vertex v is assigned a “penalty” of $\mu_v y_v$.

Extensions: Size Constraints and New Weights

- Need to cover larger set of allowed weights and discourage “large” clusters in solution. In latter case, introduce a **size bound parameter** K , and give each vertex v a parameter $\mu_v \geq 0$.
- If v is in a cluster of size $K + 1 + y_v$, where $y_v \geq 0$, then vertex v is assigned a “penalty” of $\mu_v y_v$.
- Setting all $\mu_v = 0$ gives no size bounds.

Extensions: Size Constraints and New Weights

- Need to cover larger set of allowed weights and discourage “large” clusters in solution. In latter case, introduce a **size bound parameter** K , and give each vertex v a parameter $\mu_v \geq 0$.
- If v is in a cluster of size $K + 1 + y_v$, where $y_v \geq 0$, then vertex v is assigned a “penalty” of $\mu_v y_v$.
- Setting all $\mu_v = 0$ gives no size bounds.
- If $\mu_v \geq \max_e w_e^+$, size constraints are “hard”: always profitable to split an oversized cluster.

Extensions: Size Constraints and New Weights

- Need to cover larger set of allowed weights and discourage “large” clusters in solution. In latter case, introduce a **size bound parameter** K , and give each vertex v a parameter $\mu_v \geq 0$.
- If v is in a cluster of size $K + 1 + y_v$, where $y_v \geq 0$, then vertex v is assigned a “penalty” of $\mu_v y_v$.
- Setting all $\mu_v = 0$ gives no size bounds.
- If $\mu_v \geq \max_e w_e^+$, size constraints are “hard”: always profitable to split an oversized cluster.
- Intermediate values yield “soft constraints”, where we might allow a large cluster if it has very few errors otherwise.

Extensions: Size Constraints and New Weights

- Need to cover larger set of allowed weights and discourage “large” clusters in solution. In latter case, introduce a **size bound parameter** K , and give each vertex v a parameter $\mu_v \geq 0$.
- If v is in a cluster of size $K + 1 + y_v$, where $y_v \geq 0$, then vertex v is assigned a “**penalty**” of $\mu_v y_v$.
- Setting all $\mu_v = 0$ gives no size bounds.
- If $\mu_v \geq \max_e w_e^+$, size constraints are “**hard**”: always profitable to split an oversized cluster.
- Intermediate values yield “**soft constraints**”, where we might allow a large cluster if it has very few errors otherwise.
- Deal with all these difficulties by extending CGW algorithm.

The Bounded Cluster Size Algorithm: LP Part

To accommodate weights and size constraints, modify the CGW LP as:

$$\begin{array}{ll} \text{minimize} & \left[\sum_{e \in E(G)} (w_e^+ x_e + w_e^- (1 - x_e)) \right] + \sum_{v \in V(G)} \mu_v y_v \\ \begin{array}{l} 0 \leq x_e \leq 1 \\ y_v \geq 0 \end{array} & \\ \text{subject to} & x_{uv} \leq x_{uz} + x_{zv} \quad (\forall \text{ distinct } u, v, z \in V(G)) \\ & \sum_{u \neq v} (1 - x_{uv}) \leq K + y_v \quad (\text{for all } v \in V(G)) \end{array}$$

The Bounded Cluster Size Algorithm: Rounding Up Part

Modify rounding up algorithm by introducing new parameter α :

Let $S = V(G)$.

while $S \neq \emptyset$ **do**

Let the “pivot vertex” u be an arbitrary element of S .

Let $T = \{w \in S - \{u\} : x_{uw} \leq \alpha\}$.

if $\sum_{w \in T} x_{uw} \geq \alpha |T|/2$ **then**

Output the singleton cluster $\{u\}$.

Let $S = S - \{u\}$.

else

Output the cluster $\{u\} \cup T$.

Let $S = S - (\{u\} \cup T)$.

end if

end while

Original CGW algorithm uses $\alpha = 1/2$. Need to choose α to optimize approximation ratio, based on w_e^+ , w_e^- , y_v .

Correlation Clustering: Results

- **First** correlation clustering model with **bounded cluster sizes, minimax and thresholding properties**. Accompanying approximation algorithms based on **LP relaxations** and **pivoting**.

Correlation Clustering: Results

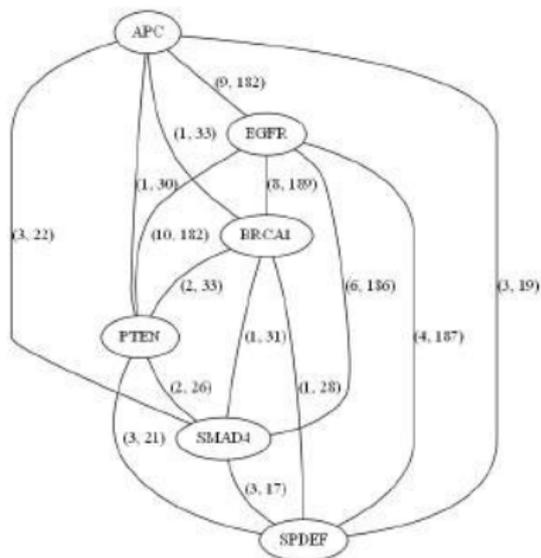
- **First** correlation clustering model with **bounded cluster sizes, minimax and thresholding properties**. Accompanying approximation algorithms based on **LP relaxations** and **pivoting**.
- Broadest range of **weight values** for which constant approximation algorithms provably exist for unconstrained, soft and hard constrained cluster sizes.

Correlation Clustering: Results

- **First** correlation clustering model with **bounded cluster sizes, minimax and thresholding properties**. Accompanying approximation algorithms based on **LP relaxations** and **pivoting**.
- Broadest range of **weight values** for which constant approximation algorithms provably exist for unconstrained, soft and hard constrained cluster sizes.
- **State-of-the-art** pathway discovery method based on mutual exclusivity analysis.

Correlation Clustering for Driver Module Analysis

Will construct **complete, weighted graph** G with vertices V indexed by genes, and edges labeled by weight vectors capturing:

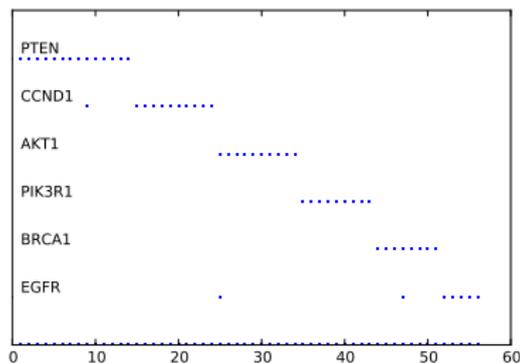


- **Mutual exclusivity:** handled via large negative weights for edges between genes that are rarely co-mutated.

EGFR/PI3K/PTEN/Akt/mTORC1 driver group.

Correlation Clustering for Driver Module Analysis

Will construct **complete, weighted graph** G with vertices V indexed by genes, and edges labeled by weight vectors capturing:



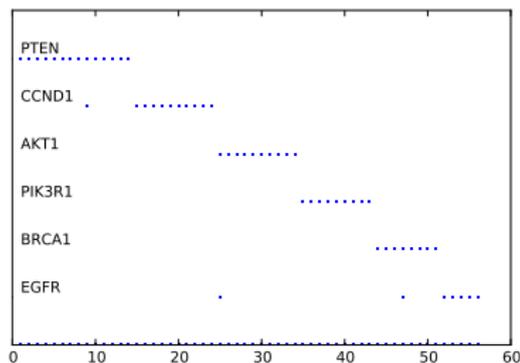
EGFR/PI3K/PTEN/Akt/mTORC1 driver group:

x-axis provides number of patients, y-axis lists genes.

- **Mutual exclusivity:** handled via large negative weights for edges between genes that are rarely co-mutated.
- **Coverage:** handled via weights of positive edges. May also include partial knowledge about network through **Kegg database**.

Correlation Clustering for Driver Module Analysis

Will construct **complete, weighted graph** G with vertices V indexed by genes, and edges labeled by weight vectors capturing:



EGFR/PI3K/PTEN/Akt/mTORC1 driver group:

x-axis provides number of patients, y-axis lists genes.

- **Mutual exclusivity:** handled via large negative weights for edges between genes that are rarely co-mutated.
- **Coverage:** handled via weights of positive edges. May also include partial knowledge about network through **Kegg database**.
- **Few pathways:** enforced via soft cluster size bounds.

Cancer Modules: Choosing the Weights

- **Parameters:** Number of patients n_p and number of genes $n_g = |V(G)|$. For each gene (i.e. vertex) u in G , $\mathcal{S}(u)$ denotes the set of patients in which u is mutated.

Cancer Modules: Choosing the Weights

- **Parameters:** Number of patients n_p and number of genes $n_g = |V(G)|$. For each gene (i.e. vertex) u in G , $\mathcal{S}(u)$ denotes the set of patients in which u is mutated.
- **TCGA Breast Cancer Dataset:** Total of $n_p = 504$ patients; $n_g = 8726$ genes.

Cancer Modules: Choosing the Weights

- **Parameters:** Number of patients n_p and number of genes $n_g = |V(G)|$. For each gene (i.e. vertex) u in G , $\mathcal{S}(u)$ denotes the set of patients in which u is mutated.
- **TCGA Breast Cancer Dataset:** Total of $n_p = 504$ patients; $n_g = 8726$ genes.
- **Negative weights:** For any $u, v \in V(G)$,

$$w_{u,v}^- = a \times \frac{|\mathcal{S}(u) \cap \mathcal{S}(v)|}{\min(|\mathcal{S}(u)|, |\mathcal{S}(v)|)},$$

where a is a user-specified relevance parameter.

Results on Cancer Modules: Choosing the Weights

- **Positive weights:** If two genes increase coverage significantly, their positive weight should be large and encourage placement in the same cluster.

Let $\mathcal{D} = \{D(u, v)\}$, $\forall u, v \in V(G)$, where

$D(u, v) = |\mathcal{S}(u) \Delta \mathcal{S}(v)|$. Let $T(J)$ be the J th percentile of the values in \mathcal{D} . Then

$$w_{uv}^+ = \begin{cases} 1 & \text{if } D(u, v) > T(J) \\ \frac{1}{T(J)} \times D(u, v) & \text{otherwise.} \end{cases}$$

Results on Cancer Modules: Choosing the Weights

- **Positive weights:** If two genes increase coverage significantly, their positive weight should be large and encourage placement in the same cluster.

Let $\mathcal{D} = \{D(u, v)\}$, $\forall u, v \in V(G)$, where

$D(u, v) = |\mathcal{S}(u) \Delta \mathcal{S}(v)|$. Let $T(J)$ be the J th percentile of the values in \mathcal{D} . Then

$$w_{uv}^+ = \begin{cases} 1 & \text{if } D(u, v) > T(J) \\ \frac{1}{T(J)} \times D(u, v) & \text{otherwise.} \end{cases}$$

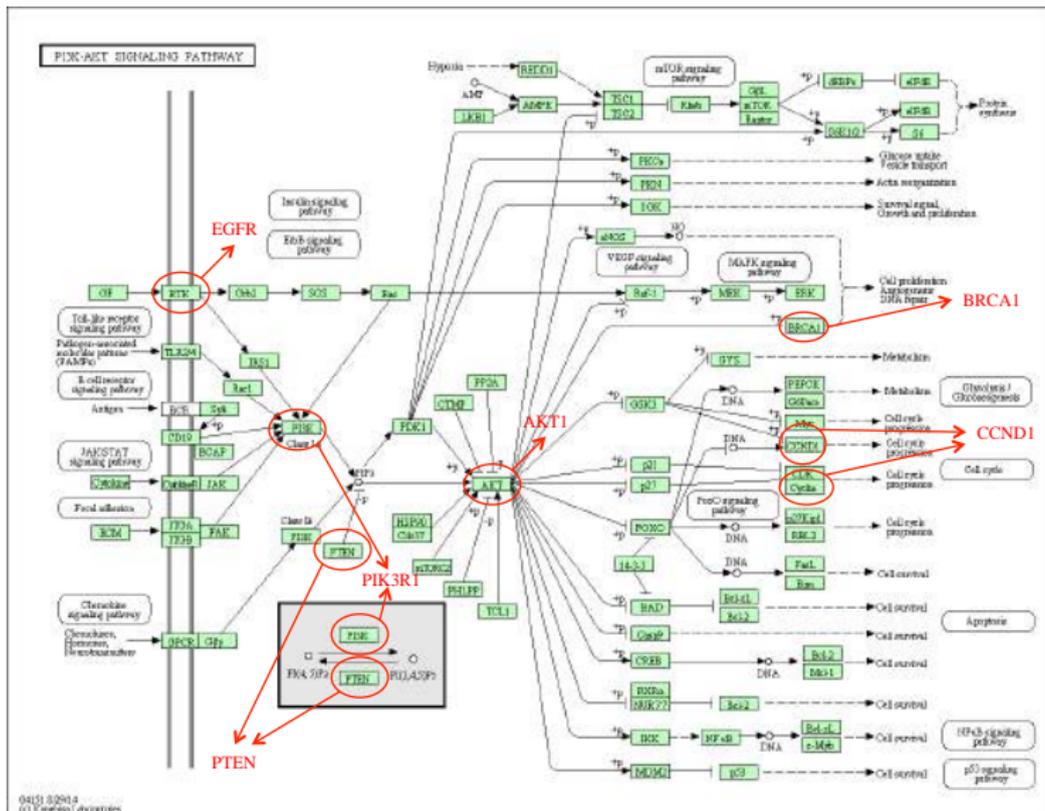
- To ensure $w_{uv}^- + w_{uv}^+ \geq 1$, for all $u, v \in V(G)$, also need

$$\text{If } w_{uv}^+ + w_{uv}^- < 1,$$

$$\text{Set } w_{uv}^- = \frac{w_{uv}^-}{w_{uv}^+ + w_{uv}^-},$$

$$\text{Set } w_{uv}^+ = 1 - w_{uv}^-.$$

Results on Modules: Uniform Modules Within a Pathway



Thank You!

Questions?